STATIC, VIBRATION AND BUCKLING ANALYSIS OF SKEW COMPOSITE AND SANDWICH PLATES UNDER THERMO MECHANICAL LOADING

S.K. SINGH* and A. CHAKRABARTI
Department of Civil Engineering
Indian Institute of Technology
Roorkee-247 667, INDIA
E-mail: sushilbit@yahoo.co.in

Static, vibration and buckling behavior of laminated composite and sandwich skew plates is studied using an efficient \( C^0 \) FE model developed based on refined higher order zigzag theory. The \( C^0 \) FE model satisfies the inter-laminar shear stress continuity at the interfaces and zero transverse shear stress conditions at plate top and bottom. In this model, the first derivatives of transverse displacement have been treated as independent variables to overcome the problem of \( C^1 \) continuity associated with the plate theory. The \( C^0 \) continuity of the present element is compensated in the stiffness matrix formulation by adding a suitable term. In order to avoid stress oscillations observed in the displacement based finite element, the stress field derived from temperature is made consistent with the total strain field by using field consistent approach. Numerical results are presented for different static, vibration and buckling problems by applying the FE model under thermo mechanical loading, where a nine noded \( C^0 \) continuous isoparametric element is used. It is observed that there are very few results available in the literature on laminated composite and sandwich skew plates based on refined theories. As such many new results are also generated for future reference.

Key words: skew plate, finite element, refined theory, thermal load.

1. Introduction

Composite materials are widely used in many engineering applications due to their high stiffness/strength to weight ratio. Laminated composite structures are weak in shear due to their low shear modulus compared to extensional rigidity. Considerable research (Reddy and Palaninathan, 1995; Jaunky et al. 1995; Wang, 1997; Babu and Kant, 1999) has been published on buckling response of skew composite laminates. In these investigations, numerical methods such as the finite element method, the Rayleigh-Ritz method, etc. are used. Reddy and Palaninathan (1995) used an triangular finite element based on the classical laminated plate theory. Jaunky et al. (1995) and Wang (1997) employed the Rayleigh-Ritz method incorporating first-order shear deformation effects. Babu and Kant (1999) presented two \( C^0 \) shear deformable finite element formulations for the buckling analysis of skew laminated composite and sandwich panels. A 16-node bi-cubic Lagrange element is used in all the formulations. Haldar (2002) and Sheikh et al. (2002) used a high precision triangular element based on the first order shear deformation theory for both cross ply and angle ply skew laminate. In all these investigations skew laminates subjected to only mechanical loads are considered. In the case of skew laminated composite and sandwich plates subjected to thermal loads, there are few studies (Prabhu and Durvasula, 1974a; 1974b; 1976) available on thermal buckling of isotropic skew plates. Kant and Babu (2000) employed higher order shear deformation theory based on finite element models for the thermal buckling analysis of skew laminated composite and sandwich plates subjected to thermal loading. Prakash et al. (2008) investigated thermal postbuckling behavior of functionally graded material of skew plates. Vosoughi et al. (2011) analyzed postbuckling behavior of laminated composite skew

* To whom correspondence should be addressed.
plates subjected to thermal loading. There are virtually no papers available in the open literature for the skew laminated composite and sandwich plates based on the refined higher order shear deformation theory. Keeping all the aspects in view an attempt has been made to analyze skew composite and sandwich plates by using a nine noded $C^0$ finite element model based on the refined higher order shear deformation theory.

2. Formulation

The in-plane displacement fields for the refined higher order zigzag theory are taken as below

$$u_\alpha = u_\alpha^0 + \sum_{k=0}^{n_u-1} S_{\alpha}^k(Z-Z_k)H(Z-Z_k) +$$

$$+ \sum_{k=0}^{n_l-1} T_{\alpha}^k(Z-\rho_k)H(-Z+\rho_k) + \xi_\alpha Z^2 + \varphi_\alpha Z^3$$

(2.1)

where $u_\alpha$ denotes the in-plane displacement of any point on the mid surface, $n_u$ and $n_l$ represent the number of upper and lower layers, respectively $S_{\alpha}^k$, $T_{\alpha}^k$, are the slopes of $k$-th layer corresponding to upper and lower layers, respectively, $\xi_\alpha, \varphi_\alpha$ are the higher order unknown terms, $H(Z-Z_k),H(Z-\rho_k)$ are unit step functions and the subscript $\alpha$ represents the co-ordinate directions $[\alpha=1, 2 \text{ i.e., } x, y \text{ in this case}]$, respectively and

$$u_2 = w(x, y).$$

(2.2)

Also, we have the stress strain relationship of a lamina, say $k$-th lamina, which may be expressed in the structural axes system ($x$-$y$) as

$$\bar{\sigma} = \left[ \begin{array}{c} \sigma_{x} \\ \sigma_{y} \\ \tau_{xy} \end{array} \right] = \left[ \begin{array}{ccc} C_{11} & C_{12} & C_{66} \\ C_{12} & C_{22} & C_{66} \\ C_{66} & C_{66} & C_{33} \end{array} \right] \left[ \begin{array}{c} \varepsilon_{x} \\ \varepsilon_{y} \\ \gamma_{xy} \end{array} \right].$$

(2.3)

Now by utilizing the transverse shear stress free condition at the top and bottom of the plate $\sigma_{3z} = 0$ the components $\xi_\alpha$ and $\varphi_\alpha$ could be expressed as

$$\Phi_\alpha = -\frac{4}{3h^2} \left( w_\alpha + \frac{1}{2} \left( \sum_{k=0}^{n_u-1} S_{\alpha}^k + \sum_{k=0}^{n_l-1} T_{\alpha}^k \right) \right),$$

(2.4)

and

$$\xi_\alpha = -\frac{1}{2} \left( \sum_{k=0}^{n_u-1} S_{\alpha}^k + \sum_{k=0}^{n_l-1} T_{\alpha}^k \right).$$

(2.5)

Similarly, by imposing the transverse shear stress continuity conditions at the layer interfaces the following expressions for $S_{\alpha}$ and $T_{\alpha}$ are obtained as below

$$S_{\alpha}^k = a_{\alpha}^k (w_{ij} + \psi_{ij}) + b_{\alpha}^k w_{ij},$$

(2.6)

$$T_{\alpha}^k = c_{\alpha}^k (w_{ij} + \psi_{ij}) + d_{\alpha}^k w_{ij}$$

(2.7)
where \( a_{xy}^k, b_{xy}^k, c_{xy}^k, d_{xy}^k \) are constants depending on material and geometric properties of individual layers, \( w_{ij} \) is the derivatives of transverse displacement while \( \gamma = 1, 2 \) and \( S_\alpha^0 = \psi_\alpha \) is the rotation of normal at the mid surface about co-ordinate directions \( \{ \alpha = 1, 2, \text{i.e., } x, y \text{ in this case} \} \).

By using Eqs (2.2)-(2.6) the strain vector can be evaluated by

\[
\{ \varepsilon \} = [H]\{ \chi \}.
\]  

(2.8)

\( \{ \varepsilon \} \) is the strain field vector \( (5 \times 1) \) and \( \{ \chi \} \) is the strain vector \( (17 \times 1) \) at the reference plane (i.e., at the mid plane) where the \([H]\) is the matrix \((5 \times 17)\) consists of terms containing \( z \) and some term related to material properties

\[
w_{ij} = \frac{\partial w}{\partial x} = w_i \quad \text{and} \quad w_{i2} = \frac{\partial w}{\partial y} = w_2,
\]  

(2.9)

\[
\{ \varepsilon \}^T = \left\{ \begin{array}{cccc}
\frac{\partial u_1^0}{\partial x} & \frac{\partial u_2^0}{\partial y} & \frac{\partial u_2^0}{\partial x} & \frac{\partial u_1^0}{\partial y} & \frac{\partial u_2^0}{\partial y} & \frac{\partial w_1}{\partial x} & \frac{\partial w_2}{\partial y} & \frac{\partial w_2}{\partial x} & \frac{\partial w_1}{\partial y} & \frac{\partial \Psi_1}{\partial x} & \frac{\partial \Psi_1}{\partial y} & \frac{\partial \Psi_2}{\partial x} & \frac{\partial \Psi_2}{\partial y} & \frac{\partial \Psi_2}{\partial x} & \frac{\partial \Psi_2}{\partial y}
\end{array} \right\},
\]  

(2.10)

The strain displacement relation may be written as below

\[
\{ \varepsilon \} = [B]\{ \delta \}
\]  

(2.11)

where \([B]\) is the strain-displacement matrix and \( \{ \delta \} \) is the element nodal displacement vector.

Thermal strain due to temperature change is given by

\[
\{ \varepsilon_{th} \} = \begin{bmatrix}
\alpha_x \Delta T \\
\alpha_y \Delta T \\
\alpha_{xy} \Delta T \\
0 \\
0
\end{bmatrix},
\]  

(2.12)

in which \( \Delta T \) is the change of temperature with respect to reference temperature, \( \alpha_x, \alpha_y, \alpha_{xy} \) are the thermal expansion coefficients in the structural axis \((x-y-z)\) system therefore, the net strain may be written as

\[
\{ \varepsilon_n \} = \{ \varepsilon \} - \{ \varepsilon_{th} \},
\]  

(2.13)

in which \( \{ \varepsilon_n \} \) is the total strain and \( \{ \varepsilon_{th} \} \) is the thermal strain, respectively.

For the present study, a nine nodedisoparametric element with seven unknowns has been used in the proposed finite element model

\[
\{ P \} = \iint \{ N \}^T q \, dx \, dy
\]  

(2.14)
where \( \{ P \} \) is the nodal force, \( \{ N \} \) is the shape functions matrix and \( q \) is the intensity of transverse load respectively.

Thermal loading may be obtained as below

\[
\{ F \} = \iint [B]^T [H]^T \{ F_N \} dxdy
\]  
\( \text{(2.15)} \)

where \( \{ F_N \}^T = \begin{bmatrix} N_x^N, N_y^N, N_{xy}^N, \text{etc.} \end{bmatrix} \) and \( \{ F \} \) is the thermal load respectively.

and

\[
\begin{bmatrix} N_x^N, N_y^N, N_{xy}^N \end{bmatrix}^T = \sum_k \int_{-1}^{1} \{ \bar{Q}_{ij} \}_k \{ e_{th} \} dz,
\]  
\( \text{(2.16)} \)

here \( i,j = 1, 2, 6 \) and \( \{ e_{th} \} \) is the thermal strain components.

It can be observed that the total strain field is always interpolated to a lower order when compared to the thermal strain fields. Hence thermal strain fields should be consistently reconstituted to the order of in-plane normal strain field to get accurate strains and stresses over the element domain. Therefore, this is accordingly taken care to make them field consistent (Naganarayana \textit{et al.}, 1997).

The following thermal case has been considered:

uniform temperature across the depth

\[
\begin{bmatrix} e_x \\ e_y \\ e_{xy} \end{bmatrix} = \begin{bmatrix} \alpha_x \\ \alpha_y \\ \alpha_{xy} \end{bmatrix} \cdot \Delta T,
\]  
\( \text{(2.17)} \)

\[
\begin{bmatrix} \alpha_x \\ \alpha_y \\ \alpha_{xy} \end{bmatrix} = \begin{bmatrix} c^2 & s^2 & -2cs \\ s^2 & c^2 & 2cs \\ cs & -cs & c^2 - s^2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_{12} \end{bmatrix}_k
\]  
\( \text{(2.18)} \)

where \( \alpha_1, \alpha_2, \alpha_{12} \) are thermal expansion coefficients in the material axis system and \( c = \cos \theta, s = \sin \theta \) and \( \theta \) is the angle between the principal material axis and structural axis.

In this case, \( \Delta T = T \), therefore, the thermal force

\[
\{ F \} = \iiint [B]^T [H]^T \begin{bmatrix} \alpha_x \\ \alpha_y \\ \alpha_{xy} \end{bmatrix} \cdot T d
\]  
\( \text{(2.19)} \)

where, \( T_u \) = temperature at top surface, \( T_b \) = temperature at bottom surface.

By applying the virtual work method, we get

\[
[k] \{ \delta \} = \{ P \}
\]  
\( \text{(2.20)} \)

where \( [k] \) is the element stiffness matrix and \( \{ P \} \) is the element nodal load vector as written below.
The element mass matrix may be written as

\[
\begin{bmatrix}
m^e
\end{bmatrix} = \sum_{k=1}^{n_{\text{vol}}} \rho_k \left[ C \right]^T [F]^T [F] \left[ C \right] dx dy dz
\] (2.21)

where \( \rho_k \) is the mass density of the \( k \)-th layer and \( [C] \) is the shape function matrix the geometric stiffness matrix \( [k_g] \) of an element may be written as

\[
\begin{bmatrix}
k_g
\end{bmatrix} = \sum_{i=1}^{n_{\text{vol}}} \iint \left[ G \right]^T \left[ S^k \right] \left[ G \right] dx dy dz
\] (2.22)

where \( [S^k] \) is the in-plane stress components of the \( k \)-th layer.

For the linear thermal buckling problems, the stability equation can be expressed as

\[
\left( [K] - \lambda \left[ K_G \right] \right) \{ \bar{e} \} = 0,
\] (2.23)

in which \([K]\) and \([K_G]\) are the global elastic and geometric stiffness matrix and \( \lambda \) is the critical temperature parameter respectively.

In the first step, a static problem is solved to calculate thermal stresses at the Gauss points of different elements for the assumed temperature rise. These thermal stresses are then used to form the matrix \([S^k]\) of the geometric stiffness matrix and the linear thermal buckling problem is solved to calculate the critical buckling temperature. Finally, the thermal vibration problem is solved an eigen value problem by taking different temperatures just below the calculated critical buckling temperature.

The equation of thermal vibration may be written as

\[
\left( [K'] - \omega^2 [M] \right) \{ \bar{v} \} = 0
\] (2.24)

where \([K'] = [K] - \lambda \left[ K_G \right] \),

in which \([K']\) is the reduced stiffness matrix, \([M]\) is mass matrix, \( \lambda \) is a fraction of critical buckling temperature and \( \omega \) is the frequency of thermal vibration, respectively.

A computer program has been written as per the above formulation. The boundary conditions used in different cases are as follows:

1. Simply supported boundary conditions on all sides (SSSS)

\[
u_1 = u_2 = w = \Psi_1 = w_1 = 0 \quad \text{at} \quad x = 0, a
\]

\[
u_1 = u_2 = w = \Psi_2 = w_2 = 0 \quad \text{at} \quad y = 0, b
\]

2. Clamped boundary conditions on all sides (CCCC)

\[
u_1 = u_2 = w = \Psi_1 = \Psi_2 = w_1 = w_2 = 0 \quad \text{at} \quad x = 0, a \quad \text{and} \quad y = 0, b
\]
3. Numerical results and discussion

Various numerical examples of skew isotropic and laminated composite plates (Fig.1) having different features are solved by the proposed $C^0$ finite element and the results obtained are presented with some published results for necessary comparison. The whole plate (Fig.1) is modeled with different mesh arrangements shown in different tables. As the sides BC and AD (Fig.1) are inclined to the global axis system ($x$-$y$), the degrees of freedom of the nodes on these two sides are transformed in the local axis system ($x'$-$y'$) for incorporation of boundary conditions for edges other than clamped. Since very few results are available in the open literature for skew plates under thermo-mechanical loading conditions, a number of numerical problems of skew plate have been solved considering different boundary conditions, ply orientations, thickness ratio and aspect ratio. The results obtained by using the proposed finite element method is first validated with the published results and many new results are generated for future reference as there is no result available in the literature based on the refined theories for skew plates according to the author’s best knowledge.

![Fig.1. Skew plate.](image)

3.1. Simply supported skew laminate ($\theta^0/90^0/\theta^0$) under uniform loading

The present problem of simply supported square cross-ply ($\theta^0/90^0/\theta^0$) skew laminate under uniform loading has been analyzed for different skew angles for the thickness ratio ($a/h$) 100 and 10. The non-dimensional central deflection $\bar{w} = \frac{10^3 w E_2 h^3}{q a^4}$ and in-plane normal stresses are given by $\bar{\sigma}_1 = \frac{h^2 \sigma_1}{qa^2}$, $\bar{\sigma}_2 = \frac{h^2 \sigma_2}{qa^2}$. The material properties of individual layers are given by: $E_1/E_2 = 25$, $G_{12} = G_{13} = 0.5 E_2$, $G_{23} = 0.2 E_2$, $\nu_{12} = \nu_{13} = 0.25$. 
The present results obtained using the proposed model based on the refined theory are presented in Tab.1 for different skew angles. The obtained results are compared with the results of Halder (2002) and Kabir (1995), respectively. The present results are in well agreement with the results of Halder (2002) and Kabir (1995), respectively.

Table 1. Non dimensional central deflection and in-plane normal stresses of a simply supported skew laminate (0°/90°/0°) subjected to uniformly distributed load.

<table>
<thead>
<tr>
<th>Thickness ratio (a/h)</th>
<th>Skew angle</th>
<th>References</th>
<th>( \bar{w} )</th>
<th>( \bar{\sigma}_1 )</th>
<th>( \bar{\sigma}_2 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>30°</td>
<td>Present (8×8)</td>
<td>0.5446</td>
<td>0.6618</td>
<td>0.2898</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.5436</td>
<td>0.6579</td>
<td>0.2799</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.5436</td>
<td>0.6579</td>
<td>0.2798</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.5452</td>
<td>0.6444</td>
<td>0.2629</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.5458</td>
<td>0.6348</td>
<td>-</td>
</tr>
<tr>
<td>45°</td>
<td></td>
<td>Present (8×8)</td>
<td>0.3577</td>
<td>0.4491</td>
<td>0.3279</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.3599</td>
<td>0.4458</td>
<td>0.3181</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.3599</td>
<td>0.4458</td>
<td>0.3181</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.3631</td>
<td>0.3007</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.3621</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>60°</td>
<td></td>
<td>Present (8×8)</td>
<td>0.1380</td>
<td>0.1971</td>
<td>0.2663</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.1432</td>
<td>0.1984</td>
<td>0.2673</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.1432</td>
<td>0.1989</td>
<td>0.2673</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.1455</td>
<td>0.2572</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.1455</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Kabir (1995)</td>
<td>0.1520</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>0.1</td>
<td>30°</td>
<td>Present (8×8)</td>
<td>0.8752</td>
<td>0.7057</td>
<td>0.4064</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.8774</td>
<td>0.7043</td>
<td>0.4073</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.8774</td>
<td>0.7040</td>
<td>0.4078</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.8621</td>
<td>0.6617</td>
<td>0.3709</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.8193</td>
<td>0.6005</td>
<td>-</td>
</tr>
<tr>
<td>45°</td>
<td></td>
<td>Present (8×8)</td>
<td>0.5625</td>
<td>0.4794</td>
<td>0.4141</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.5667</td>
<td>0.4795</td>
<td>0.4167</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.5667</td>
<td>0.4795</td>
<td>0.4167</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.5707</td>
<td>0.4543</td>
<td>0.3786</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.5507</td>
<td>0.4056</td>
<td>-</td>
</tr>
<tr>
<td>60°</td>
<td></td>
<td>Present (8×8)</td>
<td>0.2343</td>
<td>0.2089</td>
<td>0.2663</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (12×12)</td>
<td>0.2384</td>
<td>0.2104</td>
<td>0.2683</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Present (16×16)</td>
<td>0.2384</td>
<td>0.2104</td>
<td>0.2682</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Chakrabbarti (2003)</td>
<td>0.2505</td>
<td>0.2058</td>
<td>0.3023</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Haldar (2002)</td>
<td>0.2455</td>
<td>0.1758</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Kabir (1995)</td>
<td>0.2600</td>
<td>0.0832</td>
<td>-</td>
</tr>
</tbody>
</table>
3.2. Clamped isotropic skew plates

In this example, clamped isotropic skew plates with the thickness ratio \( (a/h = 100) \) have been analyzed for different skew angles subjected to a uniform temperature rise throughout the thickness. The material properties for the isotropic plate are given by

\[
\begin{align*}
E_1 &= E_2 = E_3 = 1 \text{ GPa}, \\
v_{12} &= v_{21} = 0.3, \\
G_{12} = G_{13} = G_{23} &= 0.3846 \text{ GPa}, \\
\alpha_1 &= \alpha_2 = 10^{-6} / ^\circ \text{C}.
\end{align*}
\]

The normalized critical buckling temperature is defined as follows: \( \lambda_{cr} = \alpha_0 T \) where \( T \) is the critical temperature, \( \alpha_0 \) is the normalization factor which is taken as \( = 10^{-6} \). The critical temperature \( (\lambda_{cr}) \) obtained for the thickness ratio \( (a/h = 100) \) by using the proposed FE model is shown in Tab.2. It is observed that the present results are close to the results of Prakash (2008) and Prabhu and Durvasula (1974).

Table 2. Normalized critical buckling temperature \( (\lambda_{cr} = \alpha_0 T) \) for a clamped isotropic skew plate \( (a/h = 100) \).

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0(^\circ)</td>
<td>3.7509</td>
<td>3.7374</td>
<td>3.7100</td>
</tr>
<tr>
<td>15(^\circ)</td>
<td>3.9895</td>
<td>3.9782</td>
<td>3.9500</td>
</tr>
<tr>
<td>30(^\circ)</td>
<td>4.9080</td>
<td>4.8417</td>
<td>4.800</td>
</tr>
<tr>
<td>45(^\circ)</td>
<td>7.3124</td>
<td>7.0110</td>
<td>6.9200</td>
</tr>
</tbody>
</table>

3.3. Symmetric square cross-ply \( (0^\circ/90^\circ/90^\circ/0^\circ) \) skew laminate

3.3.1.

The present problem of a symmetric cross-ply \( (0^\circ/90^\circ/90^\circ/0^\circ) \) skew laminate for different skew angles subjected to a uniform temperature rise throughout the thickness is considered. The material properties are as follows \( E_1/E_2 = 15, G_{12} = G_{13} = 0.5, G_{23} = 0.3356 E_2, v_{12} = 0.3, v_{23} = 0.49, \alpha_1/\alpha_0 = 0.015, \alpha_2/\alpha_0 = 1.0 \).

The critical buckling temperature \( (\lambda_{cr} = 10^2 \times \alpha_0 T) \) obtained for the thickness ratio \( (a/h = 100) \) by using the proposed FE model is shown in Tab.3. It is found that the results obtained using the present FE model are quite close to Kant et al. (2000) and Vosoughi et al. (2011), respectively.

Table 3. Normalized critical buckling temperature \( (\lambda_{cr} = 10^2 \times \alpha_0 T) \) for a skew laminate \( (0^\circ/90^\circ/90^\circ/0^\circ) \) \( (a/h = 100) \).

<table>
<thead>
<tr>
<th>Boundary Conditions</th>
<th>References</th>
<th>Skew angle</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>0(^\circ)</td>
</tr>
<tr>
<td>SSSS</td>
<td>Present</td>
<td>0.0998</td>
</tr>
<tr>
<td></td>
<td>Kant (2000)</td>
<td>0.0996</td>
</tr>
<tr>
<td></td>
<td>Vosoughi (2011)</td>
<td>-</td>
</tr>
<tr>
<td>CCCC</td>
<td>Present</td>
<td>0.3385</td>
</tr>
<tr>
<td></td>
<td>Kant (2000)</td>
<td>0.3348</td>
</tr>
<tr>
<td></td>
<td>Vosoughi (2011)</td>
<td>0.3446</td>
</tr>
</tbody>
</table>
3.3.2.

In this example, a symmetric cross-ply \((0^\circ/90^\circ/90^\circ/0^\circ)\) skew laminate for different skew angles subjected to uniform temperature rise throughout the thickness is considered. The material properties are same as in section 3.3.1. The critical buckling temperature \(\lambda_{cr} = 10^2 \times \alpha_a T\) obtained for the thickness ratio \((a/h =10)\) by using the proposed FE model is shown in Tab.4. It is observed that the results obtained using the present FE model are quite close to Kant et al. (2000) and Vosoughi et al. (2011), respectively.

Table 4. Normalized critical buckling temperature \(\lambda_{cr} = \alpha_a T\) for a cross-ply \((0^\circ/90^\circ/90^\circ/0^\circ)\) skew laminate \((a/h =10)\).

<table>
<thead>
<tr>
<th>Boundary Conditions</th>
<th>References</th>
<th>Skew angle</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>0(^\circ)</td>
</tr>
<tr>
<td>SSSS</td>
<td>Present</td>
<td>0.0756</td>
</tr>
<tr>
<td></td>
<td>Kant (2000)</td>
<td>0.0757</td>
</tr>
<tr>
<td></td>
<td>Vosoughi (2011)</td>
<td>-</td>
</tr>
<tr>
<td>CCCC</td>
<td>Present</td>
<td>0.1638</td>
</tr>
<tr>
<td></td>
<td>Kant (2000)</td>
<td>0.1601</td>
</tr>
<tr>
<td></td>
<td>Vosoughi (2011)</td>
<td>-</td>
</tr>
</tbody>
</table>

4. Conclusions

An analysis of skew laminated composite and sandwich skew plates is made using an efficient \(C^0\) FE model developed on the basis of the refined higher order zigzag theory. The \(C^0\) FE model satisfies the inter-laminar shear stress continuity at the interfaces and zero transverse shear stress conditions at the plate top and bottom. In this model, the first derivatives of transverse displacement have been treated as independent variables to overcome the problem of \(C^1\) continuity associated with the plate theory. The \(C^0\) continuity of the present element is compensated in the stiffness matrix formulation by adding a suitable term. It has been established through various numerical examples that the present higher order zigzag theory can accurately predict the deflection vibration and buckling of general laminated composite and sandwich plates.

Nomenclature

\[ a \] – dimension of the plate along \(x\)-axis
\[ [B] \] – strain displacement matrix
\[ [B] \] – strain-displacement matrix (derivative of shape functions)
\[ b \] – dimension of the plate along \(y\)-axis
\[ [D] \] – rigidity matrix
\[ E_1 \] – Young’s modulus in the major principal material direction of the lamina
\[ E_2 \] – Young’s modulus in the transverse material direction of the lamina
\[ E_3 \] – Young’s modulus in the transverse material direction (Per. to plane) of the lamina
\[ G_{12} \] – in-plane shear modulus
\[ G_{13}, G_{23} \] – out of plane shear moduli
\[ H(z-z_i), H(z+z_j) \] – heavy side unit step functions
\[ h \] – overall thickness of the structure
\[ h_c \] – total thickness of the core in a sandwich structure
\[ h_f \] – total thickness of face sheets in a sandwich structure
\[ [K] \] – global stiffness matrix
\([\mathbf{K}']\) – reduced stiffness matrix
\([\mathbf{K}_g]\) – global geometric stiffness matrix
\([k]^e\) – element stiffness matrix
\([k^g]\) – element geometric stiffness matrix
\([\mathbf{M}]\) – global mass matrix
\([m^e]\) – element mass matrix
\([N]\) – shape function matrix
\(n_t\) – number of layers below the mid plane of the laminated structure
\(n_u\) – number of layers above the mid plane of the laminated structure
\([\mathbf{P}]\) – global load vector
\([\mathbf{P}_e]\) – element load vector
\([\mathbf{p}]\) – element nodal load vector
\(\{\mathbf{P}\}\) – global load vector
\(\{\mathbf{P}_e\}\) – element load vector
\(\{\mathbf{p}\}\) – element nodal load vector
\(\{\mathbf{\bar{S}}^k\}\) – rigidity matrix
\(q\) – intensity of transverse loading
\(q\) – intensity of transverse load
\([s^k]\) – in-plane stress components of the \(k\)-th layer
\(S^k_\alpha\) – \(k\)-th layer corresponding to upper layers
\(S_\alpha^0 = \Psi_\alpha\) – rotation of normal at the mid surface
\(T_L\) – temperature at bottom surface
\(T_U\) – temperature at top surface
\(T^k_\alpha\) – \(k\)-th layer corresponding to lower layers
\(u^0_\alpha\) – in-plane displacement of any point on mid surface
\(x, y\) – Cartesian co-ordinates/plane
\(z\) – thickness co-ordinate/transverse direction
\(\alpha = 1, 2\) – \(x, y\) direction respectively
\(\alpha_0\) – normalization factor
\(\alpha_{1t}, \alpha_{2t}, \alpha_{12t}\) – thermal expansion coefficients in the material axis system
\(\alpha_{1x}, \alpha_{1y}, \alpha_{2y}\) – thermal expansion coefficients in the structural axis \((x-y-z)\) system
\(\beta_{1t}, \beta_{2t}, \beta_{12t}\) – moisture expansion coefficients in the material axis system
\(\beta_{1x}, \beta_{1y}, \beta_{2y}\) – moisture expansion coefficients in the structural axis \((x-y-z)\) system
\(\Delta T\) – change of temperature
\(\{\delta\}\) – nodal displacement vector
\(\{\delta\}\) – nodal unknown vector
\(\{\epsilon_{th}\}\) – thermal strain
\(\{\mathbf{\tau}\}\) – strain field vector
\(\{\tau\}\) – total strain
\(\theta\) – fiber orientation angle with respect to the principal material axis
\(\lambda\) – buckling load parameter
\(\lambda_{cr}\) – critical buckling temperature
\(\nu_{12}, \nu_{21}\) – in-plane major and minor Poisson’s ratios
\(\nu_{13}, \nu_{31}\) – out of plane \((x-z)\) major and minor Poisson’s ratios
\(\xi_{xu}, \varphi_u\) – higher order unknowns
\(\rho_c\) – mass density of core layer in a sandwich plate
\(\rho_f\) – mass density of face layer in a sandwich plate
\( \rho_i \) – mass density of the \( i \)-th layer
\( \sigma_i \) – in-plane normal stresses
\( \sigma_{xx}, \sigma_{yy} \) – in-plane normal stresses
\( \sigma_{xy}, \tau_{xy} \) – in-plane shear stress
\( \{\bar{\sigma}\} \) – stress vector at any point of the plate
\( \tau_{ij} \) – in-plane shear stress
\( \tau_{xz}, \tau_{yz} \) – transverse shear stresses
\( \{\varphi\} \) – mode shape vector for free vibration
\( \{\Psi\} \) – mode shape vector for buckling
\( \omega \) – frequency of vibration

Subscript

\( i, j \) – counters
\( k \) – counter
\( l \) – lower
\( u \) – upper
\( x \) – \( x \)-direction
\( y \) – \( y \)-direction
\( 12, 21 \) – plane directions
\( 13, 31, 23, 32 \) – transverse directions

Superscript

\( i \) – layer/interface
\( j \) – layer/interface

Abbreviations

GPa – Gega Pascal

References


Received: May 17, 2012

Revised: June 19, 2013