# EXTERNALLY AND INTERNALLY POSITIVE SINGULAR DISCRETE-TIME LINEAR SYSTEMS 

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#### Abstract

Notions of externally and internally positive singular discrete-time linear systems are introduced. It is shown that a singular discrete-time linear system is externally positive if and only if its impulse response matrix is non-negative. Sufficient conditions are established under which a single-output singular discrete-time system with matrices in canonical forms is internally positive. It is shown that if a singular system is weakly positive (all matrices $E, A, B, C$ are non-negative), then it is not internally positive.


Keywords: externally, internally, positive, singular, linear, system

## 1. Introduction

Singular (descriptor) discrete-time linear systems were considered in many papers and books (Cobb, 1984; Dai, 1989; Kaczorek, 1993; 1998b; Klamka, 1991; Lewis, 1984; 1986; Luenberger, 1977; 1978; Mertzios and Lewis, 1989; Ohta et al., 1984). The properties of fundamental matrices of singular discrete-time linear systems were established and their solution was derived in (Lewis, 1986; Mertzios and Lewis, 1989). The reachability and controllability of singular and positive linear systems were considered in (Cobb, 1984; Dai, 1989; Fanti et al., 1990; Kaczorek, 1993; Klamka, 1991; Ohta et al., 1984). The notions of weakly positive discrete-time and continuous-time linear systems were introduced in (Kaczorek, 1997; 1998a; 1998b).

In the present paper a new class of externally and internally positive discrete-time linear systems will be introduced. Necessary and sufficient conditions will be established under which singular discrete-time linear systems are externally and internally positive. It will be shown that the singular weakly positive linear system is not internally positive.

## 2. Preliminaries

Let $\mathbb{Z}_{+}$be the set of non-negative integers, $\mathbb{R}^{n \times m}$ be the set of $n \times m$ real matrices and $\mathbb{R}^{m}:=\mathbb{R}^{m \times 1}$. The set of $m \times n$ real matrices with non-negative entries will be denoted by $\mathbb{R}_{+}^{m \times n}$ and $\mathbb{R}_{+}^{m}:=\mathbb{R}_{+}^{m \times 1}$.

Consider the singular discrete-time linear system

$$
\begin{gather*}
E x_{i+1}=A x_{i}+B u_{i},  \tag{1a}\\
y_{i}=C x_{i}, \tag{1b}
\end{gather*}
$$

where $i \in \mathbb{Z}_{+}$. Here $x_{i} \in \mathbb{R}^{n}, u_{i} \in \mathbb{R}^{m}, y_{i} \in \mathbb{R}^{p}$ are the state, input and output vectors, respectively, and $E, A \in \mathbb{R}^{n \times n}, B \in \mathbb{R}^{n \times m}, C \in \mathbb{R}^{p \times n}$. It is assumed that $\operatorname{det} E=0$ and

$$
\begin{equation*}
\operatorname{det}[E z-A] \neq 0 \tag{2}
\end{equation*}
$$

for some $z \in \mathbb{C}$ (the field of complex numbers). If (2) holds, then (Kaczorek, 1993; Lewis, 1984)

$$
\begin{equation*}
[E z-A]^{-1}=\sum_{i=-\mu}^{\infty} \Phi_{i} z^{-(i+1)}, \tag{3}
\end{equation*}
$$

where $\mu$ is the nilpotence index and the $\Phi_{i}$ 's are the fundamental matrices satisfying the relations (Kaczorek, 1993; Lewis, 1984)

$$
E \Phi_{i}-A \Phi_{i-1}=\Phi_{i} E-\Phi_{i-1} A= \begin{cases}I & \text { for } i=0  \tag{4}\\ 0 & \text { for } i \neq 0\end{cases}
$$

and $E \Phi_{-\mu}=0, \Phi_{i}=0$ for $i<-\mu, I$ and 0 being the identity and zero matrices, respectively.

The solution $x_{i}$ to (1a) with admissible initial conditions is given by (Kaczorek, 1993; Lewis, 1984)

$$
\begin{equation*}
x_{i}=\Phi_{i} E x_{0}+\sum_{k=0}^{i+\mu-1} \Phi_{i-k-1} B u_{k} \tag{5}
\end{equation*}
$$

and the output $y_{i}$ is determined by the formula

$$
\begin{equation*}
y_{i}=C \Phi_{i} E x_{0}+\sum_{k=0}^{i+\mu-1} C \Phi_{i-k-1} B u_{k} . \tag{6}
\end{equation*}
$$

Let $g_{k} \in \mathbb{R}^{p \times m}, k=1-\mu, 2-\mu, \ldots, 0,1, \ldots$ be the impulse response of the system (1). Applying the superposition principle and substituting

$$
u_{k}=\left\{\begin{array}{l}
1 \text { for } k=0 \\
0 \text { for } k>0
\end{array}\right.
$$

and $x_{0}=0$ into (6), we obtain

$$
\begin{equation*}
g_{i}=C \Phi_{i-1} B \text { for } i=1-\mu, \ldots, 0,1, \ldots \tag{7}
\end{equation*}
$$

Using (7), we may write (6) in the form

$$
\begin{equation*}
y_{i}=C \Phi_{i} E x_{0}+\sum_{k=0}^{i+\mu-1} g_{i-k} u_{k} \tag{8}
\end{equation*}
$$

The transfer matrix of (1) is given by

$$
\begin{equation*}
T(z)=C[E z-A]^{-1} B \tag{9}
\end{equation*}
$$

From (3), (9) and (7) we obtain

$$
\begin{equation*}
T(z)=\sum_{i=-\mu}^{\infty} C \Phi_{i} B z^{-(i+1)}=\sum_{j=1-\mu}^{\infty} g_{j} z^{-j} \tag{10}
\end{equation*}
$$

From (10) it follows that the impulse response matrix $g_{j}$ can be found by expansion of $T(z)$.

Using (4) it can be shown that (Mertzios and Lewis, 1989)

$$
\Phi_{0} A \Phi_{i}= \begin{cases}\Phi_{i+1} & \text { for } i \geq 0  \tag{11a}\\ 0 & \text { for } i<0\end{cases}
$$

and

$$
-\Phi_{-1} E \Phi_{i}= \begin{cases}0 & \text { for } i \geq 0  \tag{11b}\\ \Phi_{i-1} & \text { for } i<0\end{cases}
$$

From (11a) we have $\Phi_{1}=\Phi_{0}\left(A \Phi_{0}\right), \Phi_{2}=\Phi_{0} A \Phi_{1}=$ $\Phi_{0}\left(A \Phi_{0}\right)^{2}$ and

$$
\begin{equation*}
\Phi_{i}=\Phi_{0}\left(A \Phi_{0}\right)^{i} \text { for } i \geq 1 \tag{12a}
\end{equation*}
$$

Similarily, from (11b) we obtain $\Phi_{-2}=-\Phi_{-1} E \Phi_{-1}$, $\Phi_{-3}=\Phi_{-1} E \Phi_{-2}=\left(-\Phi_{-1} E\right)^{2} \Phi_{-1}$ and

$$
\begin{equation*}
\Phi_{-j}=\left(-\Phi_{-1} E\right)^{j-1} \Phi_{-1} \text { for } j \geq 1 \tag{12b}
\end{equation*}
$$

## 3. Externally Positive Singular Systems

Definition 1. The singular system (1) is called externally positive if for any input sequence $u_{i} \in \mathbb{R}_{+}^{m}, i \in \mathbb{Z}_{+}$and the zero initial condition $x_{0}=0$ we have $y_{i} \in \mathbb{R}_{+}^{p}$ for $i \in \mathbb{Z}_{+}$.

Theorem 1. The system (1) is externally positive if and only if

$$
\begin{equation*}
g_{i} \in \mathbb{R}_{+}^{p \times m} \quad \text { for } i=1-\mu, \ldots, 0,1, \ldots \tag{13}
\end{equation*}
$$

Proof. The necessity follows immediately from Definition 1. To prove the sufficiency, note that for $x_{0}=0$ and $u_{k} \in \mathbb{R}_{+}^{m}, k \in \mathbb{Z}_{+}$, from (8) we obtain

$$
y_{i}=\sum_{k=0}^{i+\mu-1} g_{i-k} u_{k} \in \mathbb{R}_{+}^{p}
$$

since (13) holds.
To simplify the notation, we shall assume that $m=$ $p=1$ and

$$
\begin{align*}
& E=\left[\begin{array}{cc}
I_{n-1} & 0 \\
0 & 0
\end{array}\right] \in \mathbb{R}^{n \times n}, \\
& A=\left[\begin{array}{c:c}
0 & I_{n-1} \\
\hdashline \\
\hdashline a &
\end{array}\right] \in \mathbb{R}^{n \times n}, \\
& a=\left[\begin{array}{llllllll}
a_{0} & a_{1} & \cdots & a_{r-1} & -1 & 0 & \cdots & 0
\end{array}\right], \tag{14}
\end{align*}
$$

$$
\begin{aligned}
B & =\left[\begin{array}{c}
0 \\
\vdots \\
0 \\
1
\end{array}\right] \in \mathbb{R}^{n}, \\
C & =\left[\begin{array}{llll}
b_{0} & b_{1} & \cdots & b_{n-1}
\end{array}\right] \in \mathbb{R}^{1 \times n}
\end{aligned}
$$

Theorem 2. If the matrices $E, A, B, C$ have the canonical form (14),
and

$$
\begin{align*}
& a_{i} \geq 0, \quad i=0,1, \ldots, r-1 \\
& b_{j} \geq 0, \quad j=0,1, \ldots, n-1 \tag{15}
\end{align*}
$$

then

$$
\begin{align*}
& \Phi_{k} B \in \mathbb{R}_{+}^{n} \text { for } k=-\mu, 1-\mu, \ldots  \tag{16}\\
& \Phi_{i} \in \mathbb{R}_{+}^{n \times n} \text { for } i \in \mathbb{Z}_{+}  \tag{17}\\
& g_{j} \in \mathbb{R}_{+}^{p \times m} \text { for } j=1-\mu, 2-\mu, \ldots \tag{18}
\end{align*}
$$

Proof. If $E, A$ and $B$ have the canonical form (14), then it is easy to show that

$$
\begin{align*}
{[E z-A]_{\mathrm{ad}} B=} & {\left[\begin{array}{c}
1 \\
z \\
\vdots \\
z^{q}
\end{array}\right]=H_{q} B z^{q} } \\
& \cdots+H_{1} B z+H_{0} B \tag{19a}
\end{align*}
$$

where

$$
H_{q} B=\left[\begin{array}{c}
0  \tag{19b}\\
\vdots \\
0 \\
1
\end{array}\right], \ldots, \quad H_{0} B=\left[\begin{array}{c}
1 \\
0 \\
\vdots \\
0
\end{array}\right]
$$

From (A4) (see the Appendix) and (19) it follows that $\Phi_{k} B \in \mathbb{R}_{+}^{n}, k=-\mu, 1-\mu, \ldots, r-1$ since $H_{k} B \in \mathbb{R}_{+}^{n}$, $k=-\mu, 1-\mu, \ldots, r-1$ and $q_{k} \geq 0$ for $k=1,2, \ldots$.

From (A6) we have

$$
\begin{equation*}
\Phi_{r+k} B=\sum_{j=1}^{r} a_{r-j} \Phi_{r+k-j} B \in \mathbb{R}_{+}^{n} \quad \text { for } k=0,1, \ldots \tag{20}
\end{equation*}
$$

since by (15) we have $a_{i} \geq 0$ for $i=0,1, \ldots, r-1$.
From (A4), (A8) and (A9) we get

$$
\begin{aligned}
& \Phi_{0}=q_{\mu} H_{q}+q_{\mu-1} H_{q-1}+\cdots+q_{0} H_{r-1}
\end{aligned}
$$

where $W=\left[w_{i j}\right] \in \mathbb{R}_{+}^{(n-r) \times r}, w_{i j}=\sum_{l=1}^{j} a_{j-l} q_{i-l}$ and

$$
\begin{aligned}
& A \Phi_{0}=q_{\mu} A H_{q}+q_{\mu-1} A H_{q-1}+\cdots+q_{0} A H_{r-1} \\
& =A\left(q_{\mu} H_{q-1}+q_{\mu-1} H_{q-2}+\cdots+q_{0} H_{r-2}\right)
\end{aligned}
$$

From (12a) and (22) we have

$$
\begin{equation*}
\Phi_{i}=\Phi_{0}\left(A \Phi_{0}\right)^{i} \in \mathbb{R}_{+}^{n \times n} \quad \text { for } i=1,2, \ldots \tag{23}
\end{equation*}
$$

Using (7) and (16), we obtain

$$
\begin{equation*}
g_{j}=C \Phi_{j-1} B \in \mathbb{R}_{+}^{p \times m} \quad \text { for } j=1-\mu, 2-\mu, \ldots \tag{24}
\end{equation*}
$$

## 4. Internally Positive Singular Systems

Definition 2. The system (1) is called internally positive if for any admissible initial conditions $x_{0} \in \mathbb{R}_{+}^{n}$ and all input sequences $u_{i} \in \mathbb{R}_{+}^{m}, i \in \mathbb{Z}_{+}$we have $x_{i} \in \mathbb{R}_{+}^{n}$ and $y_{i} \in \mathbb{R}_{+}^{p}$ for $i \in \mathbb{Z}_{+}$.

From the comparison of Definitions 1 and 2 it follows that if the system (1) is internally positive, then it is always externally positive, but if the system (1) is externally positive, it may not be internally positive.

Theorem 3. The system (1) with (14) is internally positive if relations (15) hold.
Proof. By Theorem 2, if (15) hold, then $\Phi_{i} \in \mathbb{R}_{+}^{n \times n}$ for $i \in \mathbb{Z}_{+}$and $\Phi_{k} B \in \mathbb{R}_{+}^{n}$ for $k=-\mu, 1-\mu, \ldots$. Hence, using (5), we obtain $x_{i} \in \mathbb{R}_{+}^{n}$ for $i \in \mathbb{Z}_{+}$for any $x_{0} \in \mathbb{R}_{+}^{n}$ and all $u_{i} \in \mathbb{R}_{+}^{m}$. Similarly, taking into account that $g_{j} \in \mathbb{R}_{+}^{p \times m}$ for $j=1-\mu, 2-\mu, \ldots$, from (8) we obtain $y_{i} \in \mathbb{R}_{+}^{p}$ for $i \in \mathbb{Z}_{+}$.

Consider the system (1) with
$E=\left[\begin{array}{cc}I_{n-1} & 0 \\ 0 & 0\end{array}\right] \in \mathbb{R}^{n \times n}, \quad A=\left[\begin{array}{l}A_{1} \\ A_{2}\end{array}\right], \quad B=\left[\begin{array}{l}B_{1} \\ B_{2}\end{array}\right]$,
where $\quad A_{1} \in \mathbb{R}^{(n-1) \times n}, \quad A_{2} \in \mathbb{R}^{1 \times n}, \quad B_{1} \in \mathbb{R}^{n-1}$, $B_{2} \in \mathbb{R}$ and $C \in \mathbb{R}^{1 \times n}$. From (1a) for $i=0$ and (25) we have

$$
\begin{equation*}
0=A_{2} x_{0}+B_{2} u_{0} \tag{26}
\end{equation*}
$$

Equation (26) determines the set of admissible initial conditions for a given input sequence $u_{i}, i \in \mathbb{Z}_{+}$.

Note that the assumption (2) implies that $A_{2}$ is not a zero row and the singularity of the system implies that at least one entry of $A_{2}$ is zero.

From (26) for $u_{0}=0$ it follows that the equation $A_{2} x_{0}=0, x_{0} \in \mathbb{R}_{+}^{n}, x_{0} \neq 0$ can be satisfied if $A_{2}$ contains at least one positive entry and at least one negative entry. Hence we have the following important corollaries:

Corollary 1. The singular system (1) with (25) is not internally positive if $A \in \mathbb{R}_{+}^{n \times n}$.

Corollary 2. The singular weakly positive (Kaczorek, 1998a; 1998b) system (1) with (25) is not internally positive.

## 5. Example

Consider the singular system (1) with

$$
\begin{array}{ll}
E=\left[\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array}\right], \quad A=\left[\begin{array}{ccc}
0 & 1 & 0 \\
0 & 0 & 1 \\
a & -1 & 0
\end{array}\right] \\
B=\left[\begin{array}{l}
0 \\
0 \\
1
\end{array}\right], \quad C=\left[b_{0} b_{1} b_{2}\right] \tag{27}
\end{array}
$$

and $a \geq 0, b_{i} \geq 0, i=0,1,2$. In this case $n=3, r=$ $1, \mu=n-r=2$ and

$$
\begin{aligned}
{[E z-A]^{-1} } & =\left[\begin{array}{ccc}
z & -1 & 0 \\
0 & z & -1 \\
-a & 1 & 0
\end{array}\right]^{-1} \\
& =\frac{1}{z-a}\left[\begin{array}{ccc}
1 & 0 & 1 \\
a & 0 & z \\
a z & a-z & z^{2}
\end{array}\right] \\
& =\Phi_{-2} z+\Phi_{-1}+\Phi_{0} z^{-1}+\Phi_{1} z^{-2}+\cdots
\end{aligned}
$$

where

$$
\begin{align*}
& \Phi_{-2}=\left[\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 1
\end{array}\right], \quad \Phi_{-1}=\left[\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 1 \\
a & -1 & a
\end{array}\right] \\
& \Phi_{0}=\left[\begin{array}{ccc}
1 & 0 & 1 \\
a & 0 & a \\
a^{2} & 0 & a^{2}
\end{array}\right], \quad A \Phi_{0}=\left[\begin{array}{ccc}
a & 0 & a \\
a^{2} & 0 & a^{2} \\
0 & 0 & 0
\end{array}\right]  \tag{28}\\
& \Phi_{i}=\Phi_{0}\left(A \Phi_{0}\right)^{i}, \quad i \geq 1
\end{align*}
$$

Using (7), we obtain

$$
\begin{align*}
g_{-1} & =C \Phi_{-2} B=b_{2}, \\
g_{0} & =C \Phi_{-1} B=b_{1}+b_{2} a, \\
g_{1} & =C \Phi_{0} B=b_{0}+b_{1} a+b_{2} a^{2},  \tag{29}\\
g_{2} & =C \Phi_{1} B=b_{0} a+b_{1} a^{2}+b_{2} a^{3}, \\
g_{i} & =a^{i-1} g_{1}, \quad i \geq 2 .
\end{align*}
$$

From (28) and (29) it follows that for the system (1) with (27), the conditions (16)-(18) are satisfied.

The transfer function of (1) with (27) has the form

$$
\begin{equation*}
T(z)=C[E z-A]^{-1} B=\frac{b_{2} z^{2}+b_{1}^{2}+b_{0}}{z-a} . \tag{30}
\end{equation*}
$$

Expansion of (30) yields

$$
T(z)=g_{-1} z+g_{0}+g_{1} z^{-1}+g_{2} z^{-2}+\cdots
$$

where
$g_{-1}=b_{2}, \quad g_{0}=b_{1}+b_{2} a, \quad g_{1}=b_{0}+b_{1} a+b_{2} a^{2}$
and $g_{k}=a^{k-1} g_{1}$ for $k \geq 2$.
This result agrees with (29).
By Theorem 1, the system (1) with (27) is externally positive since $g_{j} \geq 0$ for $j=-1,0,1, \ldots$ By Theorem 3 , the system (1) with (27) is also internally positive.

## 6. Concluding Remarks

The notions of externally and internally positive singular discrete-time linear systems have been introduced. It has been shown that:

1. The singular discrete-time linear system (1) is externally positive if and only if its impulse response matrix $g_{i} \in \mathbb{R}_{+}^{p \times m}$ for $i>-\mu$.
2. The singular system (1) with (14) is internally positive if the conditions (15) are satisfied.
3. If the singular system (1) with (25) is weakly positive, then it is not internally positive.

The consideration presented for single-input singleoutput discrete-time linear systems can be easily extended to multi-input multi-output singular discrete-time linear systems.

An extension to singular continuous-time linear systems is also possible. A generalization of this approach to singular two-dimensional linear systems (Kaczorek, 1993) will be considered in a separate paper.

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## Appendix

## Lemma 1. Let

$$
\begin{align*}
& p(z):=\operatorname{det}[E z-A] \\
&=z^{r}-a_{r-1} z^{r-1}-\cdots-a_{1} z-a_{0}  \tag{A1}\\
& {[E z-A]_{\mathrm{ad}}=H_{q} z^{q}+\cdots+H_{1} z+H_{0} } \tag{A2}
\end{align*}
$$

and

$$
\begin{equation*}
[E z-A]^{-1}=\sum_{i=-\mu}^{\infty} \Phi_{i} z^{-(i+1)} \tag{A3}
\end{equation*}
$$

Then

$$
\left[\begin{array}{c}
\Phi_{-\mu}  \tag{A4}\\
\Phi_{1-\mu} \\
\Phi_{2-\mu} \\
\vdots \\
\Phi_{r-1}
\end{array}\right]=\left[\begin{array}{cccccc}
1 & 0 & 0 & \cdots & 0 & 0 \\
q_{1} & 1 & 0 & \cdots & 0 & 0 \\
q_{2} & q_{1} & 1 & \cdots & 0 & 0 \\
\cdots \cdots & \cdots & \cdots & \cdots & \cdots & \cdots
\end{array}\right] \cdot\left[\begin{array}{c}
H_{q} \\
H_{q-1} \\
q_{n-1}
\end{array} q_{n-2} \quad q_{n-3} \cdots \cdots q_{1} c\right]\left[\begin{array}{c}
\cdots \\
\vdots \\
H_{0}
\end{array}\right]
$$

where $n=r+\mu, \quad q=n-1$,

$$
q_{k}:=\sum_{i=1}^{k} a_{r-i} q_{k-i} \quad \text { for } \quad k=1,2, \ldots \quad\left(q_{0}:=1\right),(\mathrm{A} 5)
$$

and

$$
\begin{equation*}
\Phi_{r+k}=\sum_{j=1}^{r} a_{r-j} \Phi_{r+k-j} \quad \text { for } \quad k=0,1, \ldots \tag{A6}
\end{equation*}
$$

Proof. Using the well-known equality $[E z-A]_{\mathrm{ad}}=$ $(\operatorname{det}[E z-A])[E z-A]^{-1}$, and (A1), (A2) with (A3), we can write

$$
\begin{align*}
\left(H_{q} z^{q}+\right. & \left.H_{q-1} z^{q-1}+\cdots+H_{1} z+H_{0}\right) \\
= & \left(z^{r}-a_{r-1} z^{r-1}-\cdots-a_{1} z-a_{0}\right) \\
& \times\left(\Phi_{-\mu} z^{\mu-1}+\Phi_{1-\mu} z^{\mu-2}+\cdots\right. \\
& \left.+\Phi_{-1}+\Phi_{0} z^{-1}+\Phi_{1} z^{-2}+\cdots\right) . \tag{A7}
\end{align*}
$$

The comparison of the coefficients at the same powers of $z^{k}$ for $k=q, q-1, \ldots, 0$ of (A7) yields

$$
\begin{aligned}
\Phi_{-\mu} & =H_{q}, \quad H_{q-1}=\Phi_{1-\mu}-a_{r-1} \Phi_{-\mu} \\
\Phi_{1-\mu} & =H_{q-1}+a_{r-1} H_{q} \\
H_{q-2} & =\Phi_{2-\mu}-a_{r-1} \Phi_{1-\mu}-a_{r-2} \Phi_{-\mu} \\
\Phi_{2-\mu} & =H_{q-2}+a_{r-1} \Phi_{1-\mu}+a_{r-2} \Phi_{-\mu} \\
& =H_{q-2}+a_{r-1} H_{q-1}+\left(a_{r-1}^{2}+a_{r-2}\right) H_{q} \\
& =H_{q-2}+q_{1} H_{q-1}+q_{2} H_{q}
\end{aligned}
$$

and (A4), where $q_{k}$ is defined by (A5).

Comparing the coefficients of (A7) at $z^{-1}, z^{-2}, \ldots$, we obtain

$$
\begin{aligned}
\Phi_{r} & =a_{r-1} \Phi_{r-1}+a_{r-2} \Phi_{r-2}+\cdots+a_{0} \Phi_{0} \\
\Phi_{r+1} & =a_{r-1} \Phi_{r}+a_{r-2} \Phi_{r-1}+\cdots+a_{0} \Phi_{1}
\end{aligned}
$$

and the formula (A6).
Lemma 2. Let $H_{k}, k=0,1, \ldots, q$ be defined by (A2) and let the matrices $E, A$ have the canonical form (14). Then

$$
A H_{k}= \begin{cases}E H_{k-1}+a_{k} I_{n} & \text { for } k=1, \ldots, r-1  \tag{A8}\\ E H_{r-1}-I_{n} & \text { for } k=r \\ E H_{k-1} & \text { for } k=r+1, \ldots, q\end{cases}
$$

$$
H_{0}=\left[\begin{array}{c:c}
-a^{(0)} & \vdots \\
& \vdots \\
\cdots & \vdots \\
a_{0} I_{q} & \vdots
\end{array}\right]
$$

$$
a^{(0)}:=\left[\begin{array}{lllllll}
a_{1} & a_{2} & \cdots & a_{r-1} & -1 & 0 & \cdots
\end{array}\right]
$$

$$
H_{i}=\left[\begin{array}{cc}
-a^{(1)} & \vdots \\
\vdots & \vdots \\
-a^{(i+1)} & \vdots \\
\bar{a}^{(1)} & \vdots \\
\vdots & \vdots \\
& \vdots \\
\bar{a}^{(q-i)} & \vdots
\end{array}\right] \text { for } i=1, \ldots, r-1
$$

$$
a^{(i)}=[\overbrace{0 \cdots 0}^{i-1} a_{i+1} \cdots a_{r-1}-10 \cdots c)
$$

$$
\bar{a}^{(j)}:=[\overbrace{0 \cdots 0}^{j-1} a_{0} \cdots a_{i} 0 \cdots 0], j=1, \ldots, q-i
$$

$$
\left.H_{i}=\left[\begin{array}{cccc}
0 & \cdots & 0 & 0 \\
\cdots & \cdots & \cdots & \cdots \\
0 & \cdots & 0 & 0 \\
0 & \cdots & 0 & 1 \\
\cdots \cdots \cdots \cdots & \ldots \\
\hat{a}^{(1)} \\
\vdots \\
\hat{a}^{(i-1)}
\end{array}\right]\right\} n-i+1
$$

$$
\begin{array}{r}
\hat{a}^{(j)}:=[\overbrace{0 \cdots 0}^{j-1} a_{0} a_{1} \cdots a_{r-1}-10 \cdots 0] \\
j=1, \ldots, i-1
\end{array}
$$

$$
H_{n-1}=\left[\begin{array}{cccc}
0 & \cdots & 0 & 0  \tag{A9}\\
\cdots & \cdots & \cdots & \cdots \\
0 & \cdots & 0 & 0 \\
0 & \cdots & 0 & 1
\end{array}\right]
$$

Here $e_{i}$ is the $i$-th column of the identity matrix $I_{n}$ and $a_{i}, \quad i=0,1, \ldots, r-1$ are the coefficients of the polynomial (A1).

Proof. Using the equality $[E z-A][E z-A]_{\mathrm{ad}}=$ $I_{n} \operatorname{det}[E z-A]$ and (A1), (A2), we may write

$$
\begin{gather*}
{[E z-A]\left[H_{q} z^{q}+H_{q-1} z^{q-1}+\cdots+H_{1} z+H_{0}\right]} \\
=I_{n}\left(z^{r}-a_{r-1} z^{r-1}-\cdots a_{1} z-a_{0}\right) . \tag{A10}
\end{gather*}
$$

The comparison of the coefficients at the same powers of $z$ of (A10) yields

$$
\begin{aligned}
& A H_{0}=I_{n} a_{0}, \quad A H_{1}=E H_{0}+a_{1} I_{n}, \quad \cdots \\
& A H_{r-1}=E H_{r-2}+a_{r-1} I_{n}, \quad A H_{r}=E H_{r-1}-I \\
& A H_{r+1}=E H_{r}, \quad \cdots, \quad A H_{q}=E H_{q-1}, \quad E H_{q}=0 .
\end{aligned}
$$

It is easy to check that it satisfies the equality $A H_{0}=$ $I_{n} a_{0}$.

Using the canonical form of $E$ and $A$, it is easy to show that

$$
\begin{align*}
& {[E z-A]_{\mathrm{ad}}} \\
& =\left[\begin{array}{cccccc}
m_{11} & m_{12} & \cdots & 0 & 0 & 1 \\
a_{0} & m_{22} & \cdots & 0 & 0 & z \\
a_{0} z & a_{1} z+a_{0} & \cdots & 0 & 0 & z^{2} \\
a_{0} z^{2} & z\left(a_{1} z+a_{0}\right) & \cdots & 0 & 0 & z^{3} \\
\cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots \cdots & \cdots \cdots \cdots \cdots \\
a_{0} z^{n-3} & z^{n-4}\left(a_{1} z+a_{0}\right) & \cdots & -p(z) & 0 & z^{n-2} \\
a_{0} z^{n-2} & z^{n-3}\left(a_{1} z+a_{0}\right) & \cdots & -z p(z) & -p(z) & z^{n-1}
\end{array}\right] \\
& =H_{q} z^{q}+H_{q-1} z^{q-1}+\cdots+H_{1} z+H_{0}, \tag{A11}
\end{align*}
$$

where $m_{11}=z^{r-1}-a_{r-1} z^{r-2}-\cdots-a_{1}, \quad m_{12}=$ $=z^{r-2}-a_{r-1} z^{r-3}-\cdots-a_{2}, \quad m_{22}=z\left(z^{r-2}-\right.$ $\left.a_{r-1} z^{r-3}-\cdots-a_{2}\right), p(z)$ being defined by (A1).

The comparison of the coefficients at the same powers of $z^{k}$ for $k=0,1, \ldots, q$ of (A11) yields (A9).

